

Review Notes for Ch. 19 & beyond

Volume of

19.1 • Flux concept: Water flowing through a net.

• Oriented Surface: Normal vectors at each point on surface in a continuous way. Two possible directions to choose direction of positive flux.

For closed surfaces we default to outward orientation.

• Area Vector for a flat oriented surface

If \hat{n} is a unit-normal in positive flux direction, ~~then~~ then $\vec{A} = (\text{Area of surface})\hat{n}$

• If \vec{F} is constant and S is a flat surface with area vector \vec{A} , then

$$\text{Flux of } \vec{F} \text{ through } S = \vec{F} \cdot \vec{A} = \|\vec{F}\| \|\vec{A}\| \cos \theta$$

• If \vec{F} is not constant or S is not flat

$$\text{Flux of } \vec{F} \text{ through } S = \int_S \vec{F} \cdot d\vec{A} \quad (\text{note: } d\vec{A} = \hat{n} dA)$$

19.2 Flux Integrals for 3 Special Situations.

• if S is a portion of a surface $z = f(x, y)$, then $d\vec{A} = -f_x \vec{i} - f_y \vec{j} + \vec{k}$

• if S is ^{part of} a cylinder of radius R centered about the z -axis, then

$$d\vec{A} = (\cos \theta \vec{i} + \sin \theta \vec{j}) R dz d\theta$$

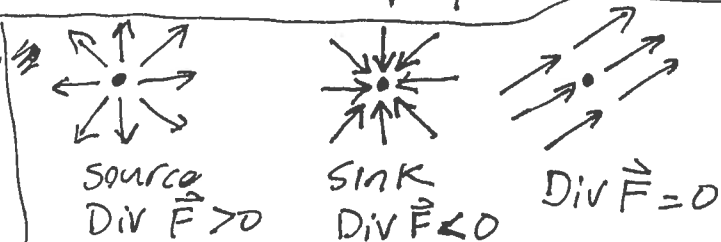
• if S is part of a sphere of radius R centered at $(0, 0, 0)$, then

$$d\vec{A} = (\sin \phi \cos \theta \vec{i} + \sin \phi \sin \theta \vec{j} + \cos \phi \vec{k}) R^2 \sin \phi d\phi d\theta$$

19.3 Divergence

• $\text{Div } \vec{F} = \text{Flux Density} = \lim_{\text{Volume} \rightarrow 0} \frac{\int_S \vec{F} \cdot d\vec{A}}{\text{Volume of } S}$

$$\text{Div } \vec{F} = \vec{\nabla} \cdot \vec{F}$$



Since $\text{Div } \vec{F} = \text{Flux density}$, we can approximate the flux ~~through~~ ^{out of} a small closed surface ^{about (a,b,c)} with Volume V by flux through $S \approx (\text{Div } \vec{F}(a,b,c))(V)$

19.4 Divergence Theorem:

If W is a solid region whose boundary S is a piecewise smooth surface, and if \vec{F} is a smooth vector field on an open region (no holes) containing W & S , then

$$\int_S \vec{F} \cdot d\vec{A} = \int_W \text{div } \vec{F} \, dV$$

"Flux of \vec{F} ~~through~~ out of $S = \text{Integral of } \text{div } \vec{F} \text{ over Region enclosed by } S."$

20.1 3D $\text{curl} = \vec{\nabla} \times \vec{F}$ is the axis about which \vec{F} would cause a magnetically suspended ping pong ball to rotate.

The direction of $\vec{\nabla} \times \vec{F}$ is given by the right hand rule, and $\|\vec{\nabla} \times \vec{F}\|$ relates to how quickly the ball would rotate.

(More formally, $\text{curl } \vec{F} = (\text{Circulation density of } \vec{F} \text{ about } \hat{n}) \hat{n}$ where \hat{n} is the axis the ball would spin about.

The circulation ^{density of \vec{F}} about a point $(a,b,c) = \text{Circ}_\alpha \vec{F}(a,b,c) = [\text{Curl } \vec{F}(a,b,c)] \cdot [\hat{n}]$

About a path C with "orientation vector" \hat{n}



20.2

Stokes' Theorem

If S is a smooth, oriented surface with a piecewise smooth, oriented boundary C , and if \vec{F} is a smooth vector field on an open region containing S & C , then

$$\int_C \vec{F} \cdot d\vec{r} = \int_S \text{curl } \vec{F} \cdot d\vec{A}$$

Circulation of \vec{F} about C = Flux of curl \vec{F} through S

